SHAIL DALAL

shail.dalal1@gmail.com | (410)344-3868 | github.com/sdalal1 | linkedin.com/shail-dalal

Northwestern University, Evanston – Robert R. McCormick School of Engineering	Sept 2023 – Present
Degree – M.S. Robotics	50pt 2025 11050h
University of Maryland, College Park – A. James Clark School of Engineering	Jan 2018 – Dec 202
Degree – B.S. Mechanical Engineering	
TECHNICAL EXPERIENCE	
Texas Instruments Dallas, TX	Jan 2023 – Aug 2023
Software Automation Developer	C
• Developed automation code using Autoshell and set-up network protocols for KLA and A	AMAT tools
• Identified and rectified a critical issue in the automation code, that was primary source of	
• Supported the semiconductor manufacturing team by adding features to increase producti	on efficiency
M.C. Dean Tysons Corner, VA	Jan 2022 – Dec 2022
Security and Electronics Project Lead	
• Developed engineering installation design packages for Electronic Security Systems, span	nning the creation of block
diagrams, riser diagrams, mounting, and wiring details in AutoCAD	
 Point of contact for technical queries for stakeholders of multiple projects 	
 Assisted in bids and proposals process to capture new projects 	
Chewy.com Wilkes-Barre, PA	Jun 2021 – Aug 202
Fulfillment Center Operations Manager Intern	
 Managed and coached a team of 60 employees regarding safety and work standards 	
• Created an Excel tracker to track safety incidents and reduce future safety incidents	
 Documented and performed 5S tasks to maintain OSHA building standards 	
	9 & Sept 2020 – Jan 2021
Mechanical Engineering Co-Op	
• Developed civil drawings of visited sites using AutoCAD and 3D models of overhead cra	
• Created automated Excel sheets to perform crane measurement calculations to increase fi	
• Supervised inspections of overhead cranes in field with third-party inspectors from intern	
Attune (SenseWare.co) Vienna, VA	Jun 2020 – Aug 2020
Hardware Engineering Intern	
 Initialized Ozone, Carbon Monoxide, and Sulphur Oxides sensors using embedded C Studied size and an initialized constrained constrained and constrained constrained and constrained constrained and constrained and	
• Studied airborne particulate monitoring sensor applications to aid COVID-19 pandemic	
I KUJEU I S/ NESEAKUH	
PROJECTS/RESEARCH Pointillism Drawing Robot Arm Evanston, IL	Sept 2023 – Dec 2023
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm 	Sept 2023 – Dec 2023
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints 	
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba 	
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories 	se
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution project 	se bhases
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD 	se
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi 	se bhases Aug 2021 – Dec 202
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi Conceptualized and designed the controller with settings to attach different hardware for the setting set to a set the set of the set o	se bhases Aug 2021 – Dec 202 testing
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi Conceptualized and designed the controller with settings to attach different hardware for to functional provided temperature changes through a webpage to remove physical presence for long 	se phases Aug 2021 – Dec 202 testing term testing
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi Conceptualized and designed the controller with settings to attach different hardware for to Integrated temperature changes through a webpage to remove physical presence for long Maryland MEMS & Microfluidics Lab College Park, MD 	se phases Aug 2021 – Dec 202 testing term testing
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi Conceptualized and designed the controller with settings to attach different hardware for to Integrated temperature changes through a webpage to remove physical presence for long Maryland MEMS & Microfluidics Lab College Park, MD Prototyped a thermocycler for a micro PCR testing device 	se bhases Aug 2021 – Dec 202 testing term testing Aug 2021 – Dec 2021
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi Conceptualized and designed the controller with settings to attach different hardware for to Integrated temperature changes through a webpage to remove physical presence for long Maryland MEMS & Microfluidics Lab College Park, MD Prototyped a thermocycler for a micro PCR testing device Controlled thermoelectric Peltier element and Pt-RTD sensors using Arduino hardware ar 	se ohases Aug 2021 – Dec 202 testing term testing Aug 2021 – Dec 2021 ad PID software
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi Conceptualized and designed the controller with settings to attach different hardware for to Integrated temperature changes through a webpage to remove physical presence for long Maryland MEMS & Microfluidics Lab College Park, MD Prototyped a thermocycler for a micro PCR testing device Controlled thermoelectric Peltier element and Pt-RTD sensors using Arduino hardware ar Assisted on integration of the thermocycler with CMOS imager and microfluidic chip of 	se ohases Aug 2021 – Dec 202 testing term testing Aug 2021 – Dec 2021 ad PID software the system
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi Conceptualized and designed the controller with settings to attach different hardware for to Integrated temperature changes through a webpage to remove physical presence for long Maryland MEMS & Microfluidics Lab College Park, MD Prototyped a thermocycler for a micro PCR testing device Controlled thermoelectric Peltier element and Pt-RTD sensors using Arduino hardware ar Assisted on integration of the thermocycler with CMOS imager and microfluidic chip of 	se ohases Aug 2021 – Dec 202 testing term testing Aug 2021 – Dec 2021 ad PID software the system
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi Conceptualized and designed the controller with settings to attach different hardware for to Integrated temperature changes through a webpage to remove physical presence for long Maryland MEMS & Microfluidics Lab College Park, MD Prototyped a thermocycler for a micro PCR testing device Controlled thermoelectric Peltier element and Pt-RTD sensors using Arduino hardware ar Assisted on integration of the thermocycler with CMOS imager and microfluidic chip of Northrop Grumman COVID-19 AI Challenge College Park, MD (Virtual) Developed AI bot to provide information on COVID-19 using Keras and TensorFlow 	se se Aug 2021 – Dec 202 testing term testing Aug 2021 – Dec 2021 and PID software the system Jan 2021 – May 2021
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi Conceptualized and designed the controller with settings to attach different hardware for to Integrated temperature changes through a webpage to remove physical presence for long Maryland MEMS & Microfluidics Lab College Park, MD Prototyped a thermocycler for a micro PCR testing device Controlled thermoelectric Peltier element and Pt-RTD sensors using Arduino hardware ar Assisted on integration of the thermocycler with CMOS imager and microfluidic chip of Northrop Grumman COVID-19 AI Challenge College Park, MD (Virtual) Developed AI bot to provide information on COVID-19 using Keras and TensorFlow Integrated mask detection using OpenCV Haar Cascade Classifier and Google speech rec 	se se Aug 2021 – Dec 202 testing term testing Aug 2021 – Dec 202 ad PID software the system Jan 2021 – May 202
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi Conceptualized and designed the controller with settings to attach different hardware for to Integrated temperature changes through a webpage to remove physical presence for long Maryland MEMS & Microfluidics Lab College Park, MD Prototyped a thermocycler for a micro PCR testing device Controlled thermoelectric Peltier element and Pt-RTD sensors using Arduino hardware ar Assisted on integration of the thermocycler with CMOS imager and microfluidic chip of Northrop Grumman COVID-19 AI Challenge College Park, MD (Virtual) Developed AI bot to provide information on COVID-19 using Keras and TensorFlow Integrated mask detection using OpenCV Haar Cascade Classifier and Google speech rec Collaborated with 4 students and placed 2nd among 15 participating teams 	se ohases Aug 2021 – Dec 202 testing term testing Aug 2021 – Dec 2021 and PID software the system Jan 2021 – May 2021 ognition API
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python Movelt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi Conceptualized and designed the controller with settings to attach different hardware for to Integrated temperature changes through a webpage to remove physical presence for long Maryland MEMS & Microfluidics Lab College Park, MD Prototyped a thermocycler for a micro PCR testing device Controlled thermoelectric Peltier element and Pt-RTD sensors using Arduino hardware ar Assisted on integration of the thermocycler with CMOS imager and microfluidic chip of Northrop Grumman COVID-19 AI Challenge College Park, MD (Virtual) Developed AI bot to provide information on COVID-19 using Keras and TensorFlow Integrated mask detection using OpenCV Haar Cascade Classifier and Google speech rec Collaborated with 4 students and placed 2nd among 15 participating teams Raspberry Pi Projects College Park, MD 	se ohases Aug 2021 – Dec 202 testing term testing Aug 2021 – Dec 2021 and PID software the system Jan 2021 – May 2021 ognition API Jan 2021 – Apr 2021
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python MoveIt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi Conceptualized and designed the controller with settings to attach different hardware for to Integrated temperature changes through a webpage to remove physical presence for long Maryland MEMS & Microfluidics Lab College Park, MD Prototyped a thermocycler for a micro PCR testing device Controlled thermoelectric Peltier element and Pt-RTD sensors using Arduino hardware ar Assisted on integration of the thermocycler with CMOS imager and microfluidic chip of Northrop Grumman COVID-19 AI Challenge College Park, MD (Virtual) Developed AI bot to provide information on COVID-19 using Keras and TensorFlow Integrated mask detection using OpenCV Haar Cascade Classifier and Google speech rec Collaborated with 4 students and placed 2nd among 15 participating teams Raspberry Pi Projects College Park, MD Utilized Python to create lane detection and facial detection module for a pre-recorded vior 	se ohases Aug 2021 – Dec 202 testing term testing Aug 2021 – Dec 2021 and PID software the system Jan 2021 – May 2021 ognition API Jan 2021 – Apr 2021 deo
 Pointillism Drawing Robot Arm Evanston, IL Built a ROS package to draw pointillism art using a Franka Emika Panda arm Implemented canny edge detection to convert images to points to be used as waypoints Developed a computer vision algorithm to identify location of paint colors from robot ba Designed a custom Python Movelt API to execute accurate painting and dot trajectories Headed version control for project repository and contributed to planning and execution p Glass Testing Temperature Cycler College Park, MD Prototyped a PID temperature cycler for glass testing using a Raspberry Pi Conceptualized and designed the controller with settings to attach different hardware for to Integrated temperature changes through a webpage to remove physical presence for long Maryland MEMS & Microfluidics Lab College Park, MD Prototyped a thermocycler for a micro PCR testing device Controlled thermoelectric Peltier element and Pt-RTD sensors using Arduino hardware ar Assisted on integration of the thermocycler with CMOS imager and microfluidic chip of Northrop Grumman COVID-19 AI Challenge College Park, MD (Virtual) Developed AI bot to provide information on COVID-19 using Keras and TensorFlow Integrated mask detection using OpenCV Haar Cascade Classifier and Google speech rec Collaborated with 4 students and placed 2nd among 15 participating teams 	se ohases Aug 2021 – Dec 202 testing term testing Aug 2021 – Dec 202 nd PID software the system Jan 2021 – May 202 ognition API Jan 2021 – Apr 2021 deo

Software – Robot Operating System (ROS), Git, Python, MATLAB, C++, Concurrent Versions System(CVS), AutoShell, CSS, HTML, Shell Scripting (Bash), OpenCV, Linux, Solaris

Design Software – AutoCAD, SolidWorks, Autodesk Fusion 360, Autodesk Inventor, Creo, Onshape **Hardware** – Raspberry Pi, Arduino, Nordic nRF52833 (Microbit), Jetson Nano